DANIEL T. SHORES

MECHANICAL ENGINEER • USA CITIZEN

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EDUCATION

NORTHEASTERN UNIVERSITY

BOSTON, MASSACHUSETTS USA

AUGUST 2016

MASTER OF SCIENCE, MECHANICAL ENGINEERING

CONCENTRATION IN MECHANICS

GPA: 3.45 (maximum grade point average 4.0)

Courses Mathematical Methods for Mechanical Engineers, Advanced Mechanics of Materials,

Mechatronics, Finite Element Methods, Dynamics and Mechanical Vibration

Environmental Issues in Manufacturing and Product Use

THESIS DEVELOPMENT OF PATIENT SPECIFIC NEONATAL CATHETERS USING 3D MAGNETIC

PRINTING

January 2016 – June 2016 (Spring 2016 & Summer I 2016 Semesters)

Supervisor: Dr Randall Erb, Assistant Professor

College of Engineering, Mechanical and Industrial Engineering

NORTHEASTERN UNIVERSITY

BOSTON, MASSACHUSETTS USA

DECEMBER 2015

BACHELOR OF SCIENCE, MECHANICAL ENGINEERING

GPA: 3.45 (maximum grade point average 4.0)

Systems Analysis and Control, Heat Transfer, Thermodynamics, Fluid Mechanics, Mathematical Methods for ME, Mechanics of Materials, Mechanics (Statics and Dynamics), Material Science, Engineering Problem Solving (MATLAB, C++)

SENIOR DESIGN DIRECT-WRITE 3D PRINTER FOR ALIGNED DISCONTINUOUS FIBER COMPOSITES

July – December 2015 (Summer II 2015 & Autumn 2015 semesters)

HONORS DEAN'S SCHOLARSHIP, 2011-2016

DEAN'S LIST (3.5 or better GPA during a semester)

Spring 2012 and Autumn 2012

Autumn 2013 Autumn 2015

CO-OP WORK BOSTON DEVICE DEVELOPMENT, Newton, Massachusetts USA

January - June 2015

FARM DESIGN, Hollis, New Hampshire USA

January - June 2014

FIKST PRODUCT DEVELOPMENT, Woburn, Massachusetts USA

January - June 2013

EXTRA- BIOMEDICAL ENGINEERING SOCIETY, NORTHEASTERN UNIVERSITY CHAPTER

CURRICULAR Co-Founder; Vice President, 2012-2013; Treasurer 2014; President 2015

NORTHEASTERN UNIVERSITY OUTDOORS CLUB Trip Leader, 2012-2015; Vice President, 2013

GEORGETOWN HIGH SCHOOL GEORGETOWN, MASSACI

GEORGETOWN, MASSACHUSETTS USA June 2011

GPA: 3.8 (maximum grade point average 4.0)

LEADERSHIP STUDENT COUNCIL: PRESIDENT, 2010/2011

VARSITY CROSS-COUNTY RUNNING CAPTAIN, 2010

CERTIFICATIONS Solidworks Professional – Mechanical Design, *June 2014*

MITx Intro to Comp. Sci. and Programming Using Python, April 2014

Six Sigma Specialist, August 2012

WORK EXPERIENCE

BOSTON DEVICE Product development consultancy focused on consumer and early-stage clients

DEVELOPMENT MECHANICAL ENGINEERING CO-OP Jan – June 2015 Newton, Massachusetts USA

SUMMARY Built and troubleshot a 3 meter tall factory pill sorting robot prototype consisting of a 3-axis

gantry upper system and a 2-axis lower system and developed the works-like, looks-like beta prototype of a butane powered curling iron and straightener. Projects were completed

in teams of 2-3 with weekly meetings with the clients.

FARM DESIGN Product development consultancy focused on biomedical clients

Jan – June 2014 Mechanical Engineering Co-op

Hollis, New Hampshire USA

SUMMARY Brainstormed, designed, sourced parts, and built the base frame subsystem of a 5-week

medical robot stability and transportation concept prototype project; developed the motherboard and performed testing for a neurological ablation system; and built and documented the pneumatic controller prototype for a controlled diagnostic device. Projects

were completed independently as portions of larger projects with teams of 4-6.

FIRST PRODUCT Product development consultancy focused on biomedical and consumer clients

DEVELOPMENT MECHANICAL ENGINEERING CO-OP Jan – June 2013 Woburn, Massachusetts USA

SUMMARY Conducted brainstorming, initial design, CAD, and alpha prototyping of a golf ball thrower

for FlingGolf and performed research, constructed a complex theoretical model, and designed components to solve balance and vibration issues in a rotating medical device. Projects were completed independently under the guidance of a principal engineer and

involved weekly client meetings.

RAYTHEON - IDS Private Defense Contractor focused on quided missile systems

May – Aug 2012 Mechanical Engineering Intern

Andover, Massachusetts USA

SUMMARY Contributed to manufacturing floor support team for Patriot Radar System; tracked radar shelter non-conformances and generated engineering change proposals; and conducted a

company improvement project concerning environmental testing performed on COTS items

used by Raytheon

RESEARCH PROJECTS

MASTER'S THESIS Development of Patient Specific Neonatal Catheters Using 3D Magnetic Printing

Northeastern University, January-June 2016 Supervisor: Dr Randall Erb, Assistant Professor

Summary Samples of varying ceramic fiber reinforcement orientations and polymer materials were

printed using an aligned discontinuous fiber composite prototype 3D printer and tested for mechanical strength properties. From these properties, an FEA model was built which allows for rapid design and printing of a customized, high strength intravascular catheter

small enough to be used in neonatal procedures.

SENIOR DESIGN Direct-Write 3D Printer For Aligned Discontinuous Fiber Composites

Northeastern University, July - Dec 2015

SUMMARY Built a direct-write 3D printer capable of printing a specific aligned composite material with

exceptional strength to weight ratio. Team of five student engineers. In charge of syringe

pump development and control as well as printer integration and communication.

SKILLS

TECHNICAL Mill, Arduino, 3D Printer, Laser Cutter, DFM, Engineering Drawings

COMPUTER Solidworks, Pro/E, ANSYS, Excel, Python, MATLAB, Simulink, LabView